

A decentralised diagnosis method with probabilistic cellular automata

Irène Marcovici

Joint work with Nazim Fatès and Régine Marchand

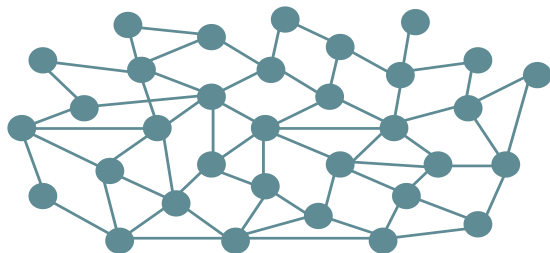
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GrHyDy 2024
October 23, 2024



- 1 The decentralised diagnosis problem
- 2 First rule (isotropic)
- 3 A little digression: bootstrap percolation
- 4 Second rule (directional)

- Distributed network, made of interconnected components that interact with their neighbours.



Neutral

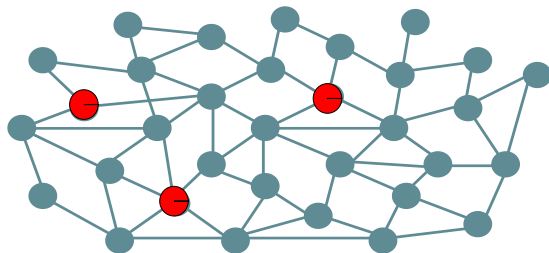


Defect



Alert

- Distributed network, made of interconnected components that interact with their neighbours.
- The components can be subject to **failures**.



Neutral

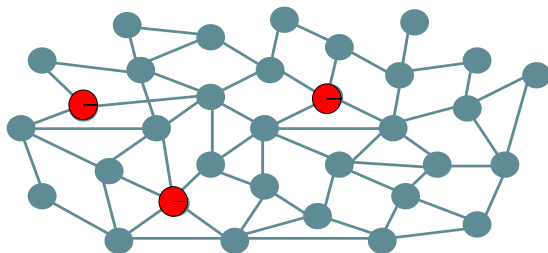


Defect



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- When the density of failures is **below** a given threshold, some components should still operate in the neutral state.



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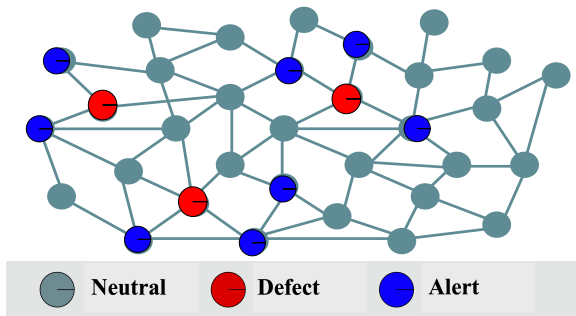


Defect

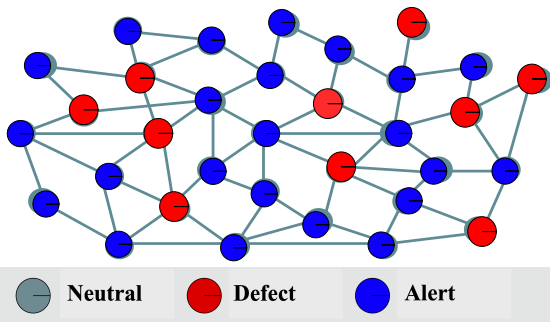


Alert

- When the density of failures is **below** a given threshold, some components should still operate in the neutral state.



- When the density of failures is **below** a given threshold, some components should still operate in the neutral state.
- When the density is **beyond** this threshold, all the components should be in the alert state.



Aim: give the entities a set of instructions to achieve this.

The goal is to gather a **global** information by exchanging only **local** information (consensus-building / self-organization).

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The goal is to gather a **global** information by exchanging only **local** information (consensus-building / self-organization).

Difficulties:

- it is not possible to centralize information (entities all play the same role),
- conventional counting techniques cannot be used (entities have a limited memory).

Lattice \mathbb{Z}^2 , on which each cell can be in 3 possible states:

- **N** : neutral,
- **D** : defect (it is a fixed state),
- **A** : alert.

Objective

Find the simplest possible local rule such that, starting from an initial config. with **N** and **D** (indep.), state **A** invades the grid iff the density of **D** exceeds a certain threshold (which we would like to be able to choose).

Let S be a finite set, and $d \geq 1$.

A function $F : S^{\mathbb{Z}^d} \rightarrow S^{\mathbb{Z}^d}$ is a **cellular automaton** if there exists a finite **neighbourhood** $\mathcal{N} \subset \mathbb{Z}^d$ a **local function** $f : S^{\mathcal{N}} \rightarrow S$ such that :

$$\forall x \in S^{\mathbb{Z}^d}, \forall k \in \mathbb{Z}^d, \quad F(x)_k = f((x_{k+i})_{i \in \mathcal{N}}).$$

$$\begin{array}{c}
 F(x) = \dots \boxed{?} \boxed{?} \boxed{?} \boxed{?} \boxed{?} \boxed{?} \boxed{?} \boxed{?} \boxed{?} \boxed{?} \boxed{?} \boxed{?} \boxed{?} \boxed{?} \boxed{?} \dots \\
 x = \dots \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \dots
 \end{array}$$



$$S = \{\square, \blacksquare\}, \mathcal{N} = \{-1, 0, 1\}$$

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$$x = \cdots \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \boxed{} \cdots$$

$\uparrow f$

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For **probabilistic** CA, the local rule gives, for each element of $S^{\mathcal{N}}$, the probability of each state.

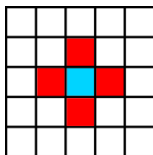
$$f : S^{\mathcal{N}} \rightarrow \mathcal{M}(S) \quad F : \mathcal{M}(S^{\mathbb{Z}^d}) \rightarrow \mathcal{M}(S^{\mathbb{Z}^d})$$

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- If all neighbours are **N**, the new state is **N**.
- If all neighbours are **A** or **D**, the new state is **A**.
- Otherwise, the new state of the cell is:

$$\begin{aligned} \mathbf{N} \text{ with proba. } & \frac{\exp(\lambda n_N)}{\exp(\lambda n_N) + \exp(\lambda(n_A + n_D))} \\ \mathbf{A} \text{ with proba. } & \frac{\exp(\lambda(n_A + n_D))}{\exp(\lambda n_N) + \exp(\lambda(n_A + n_D))}, \end{aligned}$$

where n_N , n_A , n_D are resp. the nb. of neighbours **N**, **A**, **D**.



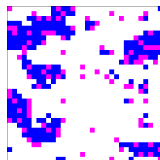
von Neumann neighbourhood

Evolution of a random configuration with $L = 32$, and $\lambda = 1$.

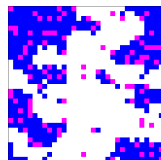
Density of defects $d_D = 0.1$: the alert state invades the whole grid.



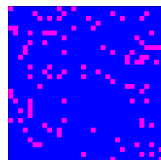
$t = 0$



$t = 20$



$t = 40$



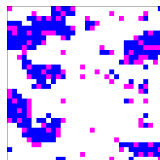
$t = 260$

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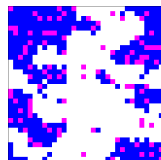
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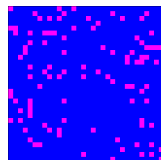
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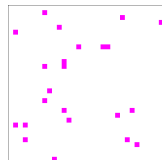


$t = 40$

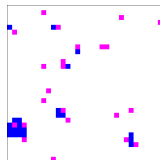


$t = 260$

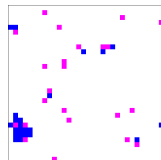
Density of defects $d_D = 0.02$: the diffusion of the alert state remains bounded.



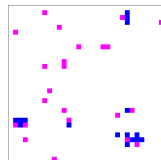
$t = 0$



$t = 1000$



$t = 10000$



$t = 40000$

Experimental observations:

- ⊕ suitable for practical use on finite grids (the parameter λ allows to adjust the threshold of defects),

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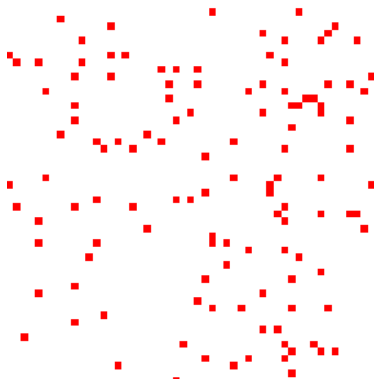
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- ⊖ the experimental threshold depends on the size of the grid.

↪ It certainly does not work on the entire \mathbb{Z}^2 lattice.

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- Cells in state 0 with ≥ 2 neighb. in state 1 become in state 1.

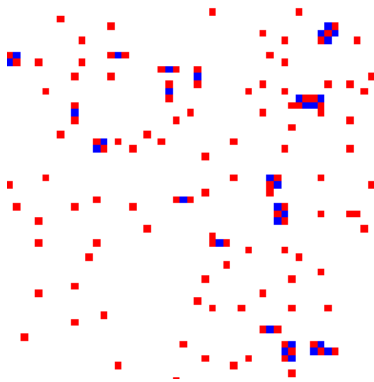
Simulation with $d_1 = 0.05$.



Step 0

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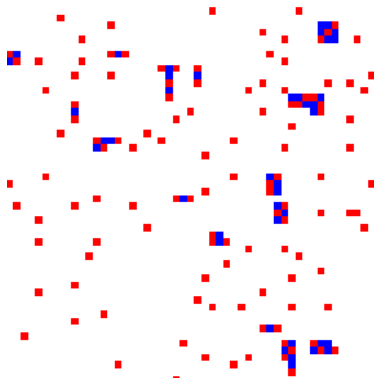
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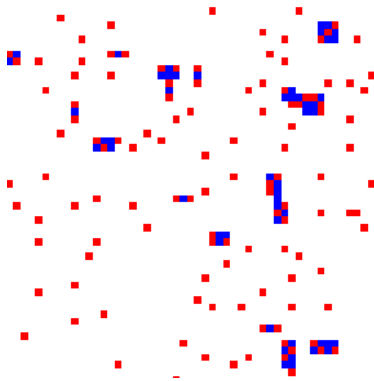
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Step 2

- Cells in state 1 always remain in state 1.
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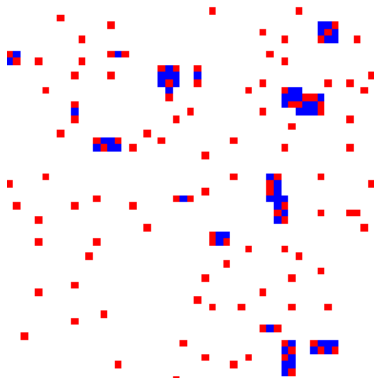
Simulation with $d_1 = 0.05$.



Step 3

- Cells in state 1 always remain in state 1.
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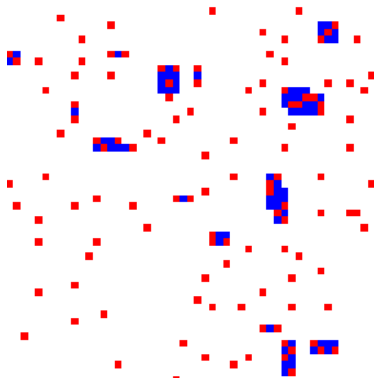
Simulation with $d_1 = 0.05$.



Step 4

- Cells in state 1 always remain in state 1.
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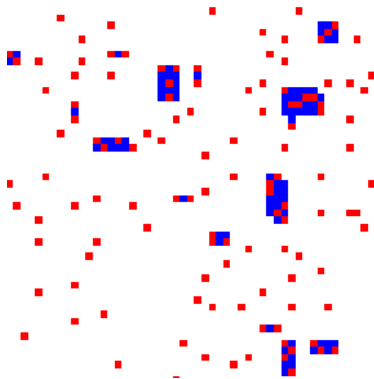
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Step 5

- Cells in state 1 always remain in state 1.
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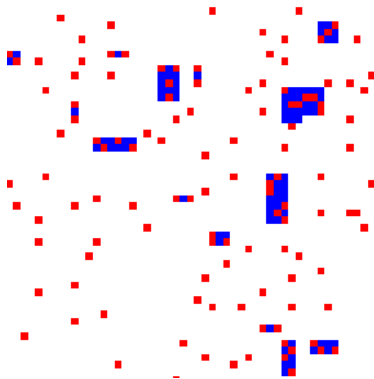
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Step 6

- Cells in state 1 always remain in state 1.
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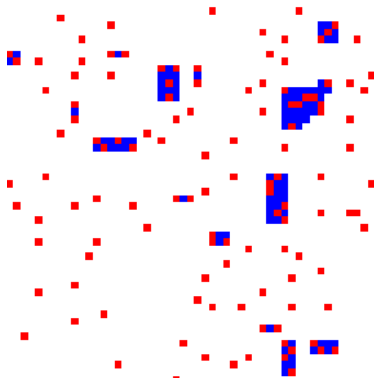
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Step 7

- Cells in state 1 always remain in state 1.
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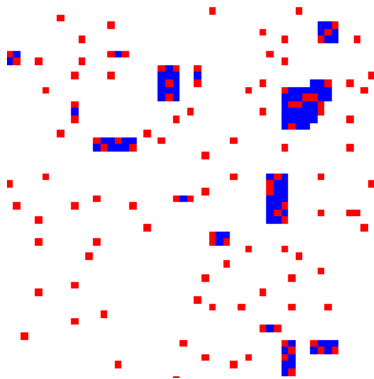
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Step 8

- Cells in state 1 always remain in state 1.
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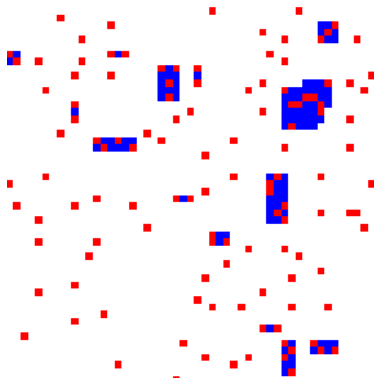
Simulation with $d_1 = 0.05$.



Step 9

- Cells in state 1 always remain in state 1.
- Cells in state 0 with ≥ 2 neighb. in state 1 become in state 1.

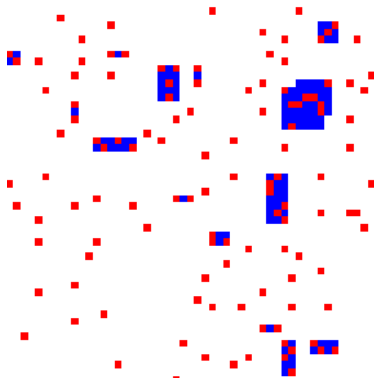
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Step 10

- Cells in state 1 always remain in state 1.
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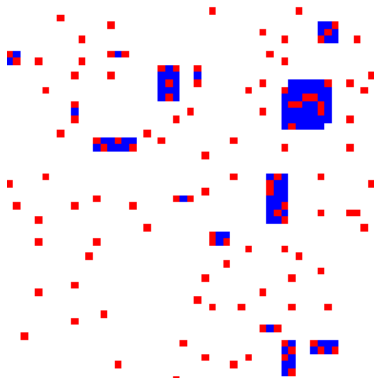
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Step 11

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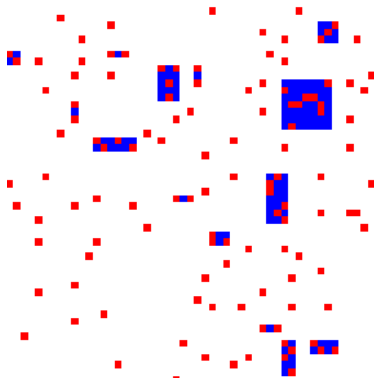
Simulation with $d_1 = 0.05$.



Step 12

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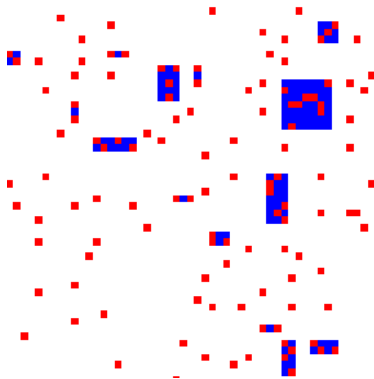
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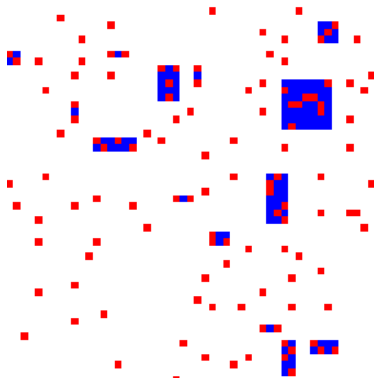
Simulation with $d_1 = 0.05$.



Step 14

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Simulation with $d_1 = 0.05$.



Step 15

Theorem [van Enter 1987]

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Idea: prove that there is somewhere in the initial configuration an “all 1” square from which the whole configuration will be invaded.

This will happen iff this square is not surrounded by an “all 0” rectangle.

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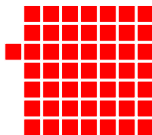


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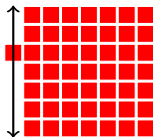


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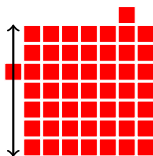


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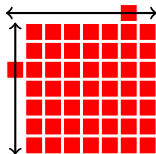


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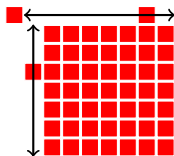


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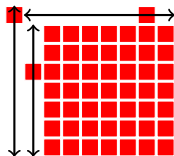


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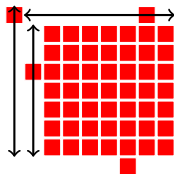


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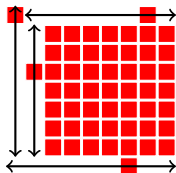


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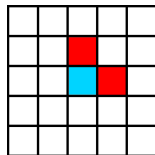


Remark: on a large $N \times N$ grid, Holroyd has proven in 2003 that

- $d_1 > \frac{\pi^2}{18 \log N} \implies$ conv. to total occupancy with high prob,
- $d_1 < \frac{\pi^2}{18 \log N} \implies$ no convergence to total occupancy.

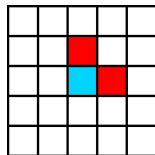
NE-bootstrap percolation

- Cells in state 1 always remain in state 1.
- Cells in state 0 with North and East neighb. in state 1 become in state 1.



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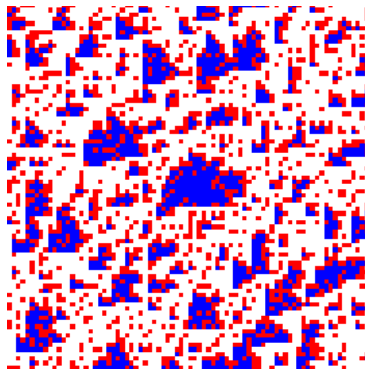


Proposition

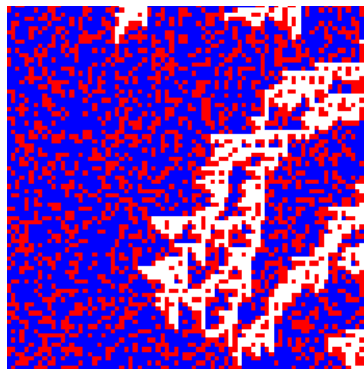
There exists $\beta_c \in (0, 1)$ such that:

- for $d_1 < \beta_c$, state 1 does not invade the whole grid,
- for $d_1 > \beta_c$, state 1 invades the grid.

$\beta_c = 1 - p_c \approx 0.29$, where $p_c =$ threshold for directed site percol.



$d_1 = 0.25$

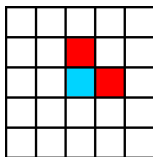


$d_1 = 0.35$

(150 iterations)

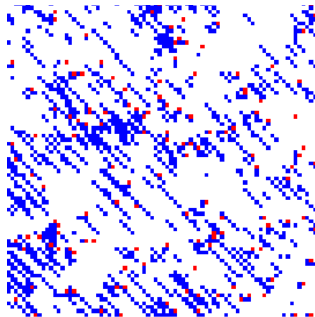
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Previous rule on NE-neighb., with additional simplifications...



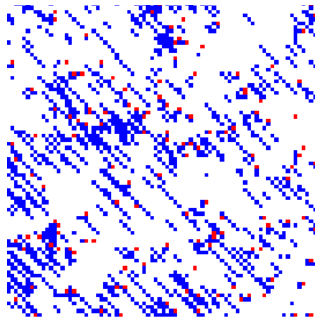
- If the two (red) neighb. are **N**, the new state is **N**.
- If the two (red) neighb. are **A** or **D**, the new state is **A**.
- Otherwise, state is **A** with prob. p and **N** with prob. $1 - p$.

Parameter $p = 0.4$ (200 iterations)

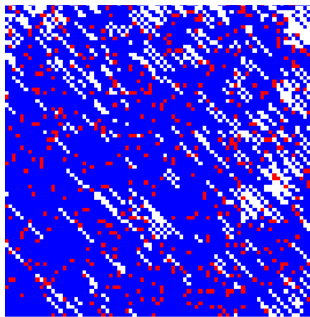


$$d_D = 0.02$$

Parameter $p = 0.4$ (200 iterations)



$d_D = 0.02$



$d_D = 0.08$

Proposition [Fatès-Marchand-M. 2023]

Initial config. with a single cell in state A and no D

T = extinction time

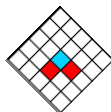
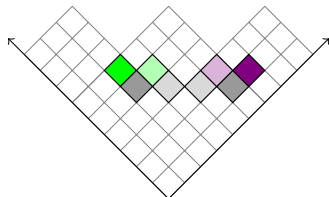
- For $p < 1/2$, T is a.s. finite and $\mathbb{E}(T) < +\infty$.
- For $p = 1/2$, T is a.s. finite and $\mathbb{E}(T) = +\infty$.
- For $p > 1/2$, $\mathbb{P}(T = +\infty) > 0$.

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Proof: at any time, the config. is either empty or an horiz. A segment. The right boundary evolves as a random walk with steps $1/2$ with prob. p and $-1/2$ with prob. $1 - p$.

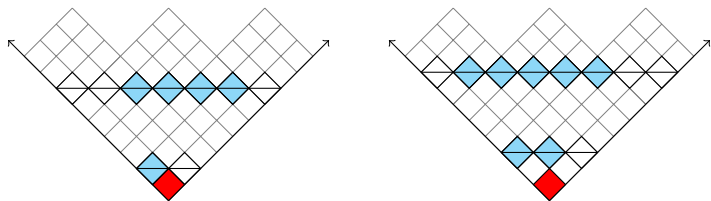
Proposition [Fatès-Marchand-M. 2023]

Initial config. with a single cell in state D and no A

T = first return time

- For $p < 1/2$, T is a.s. finite and $\mathbb{E}(T) < +\infty$.
- For $p \geq 1/2$, $\mathbb{P}(T = +\infty) > 0$.

Proof: previous proposition + Foster's theorem.



Theorem [Fatès-Marchand-M. 2023]

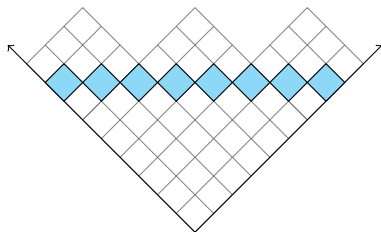
For $p \in (0, \beta_c)$, there exists $d_D^c(p)$ such that:

- for $d_D > d_D^c(p)$, state **A** invades the grid,
- for $d_D < d_D^c(p)$, state **A** does not invade the whole grid.

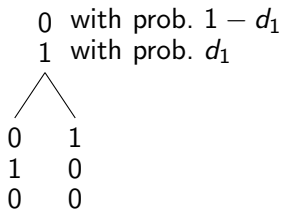
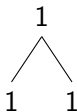
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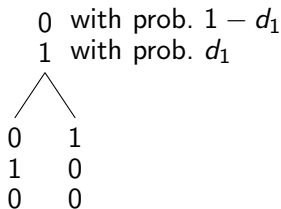
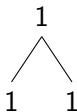
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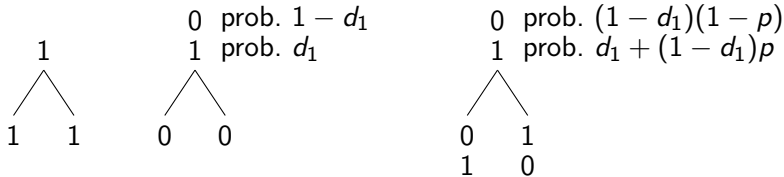
NE-bootstrap



NE-bootstrap



Our directional rule, with $1 = \{D, A\}$, $0 = N$



$$\text{NE-bootstrap}(d_1) \preceq \text{PCA}(p, d_1) \preceq \text{NE-bootstrap}(d_1 + (1 - d_1)p)$$

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The rule is stoch. increasing with d_1 , so for a fixed $p \in (0, \beta_c)$, increasing d_1 takes us from the coexistence to the invasion regime.

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The rule is stoch. increasing with d_1 , so for a fixed $p \in (0, \beta_c)$, increasing d_1 takes us from the coexistence to the invasion regime.

Corollary: $\frac{\beta_c - p}{1 - p} \leq d_D^c(p) \leq \beta_c$, so $\lim_{p \rightarrow 0} d_D^c(p) = \beta_c$.

Conjecture: the prop. still holds for $p \in (0, 1/2)$ and $\lim_{p \rightarrow 1/2} d_D^c(p) = 0$, so one can detect any threshold of defects between 0 and β_c .

- **First rule:**

- ⊖ difficult to analyse, no phase transition on \mathbb{Z}^2 ,
- ⊕ isotropic, can be extended to irregular networks.

- **Second rule:**

- ⊖ artificial direction for the flow of information,
- ⊕ tractable model, phase transition on \mathbb{Z}^2 .

- **Perspectives:**

- extend the analytical study of the two rules,
- defects that appear dynamically,
- other lattices, random graphs.

A decentralised diagnosis method with probabilistic cellular automata.

Nazim Fatès, Régine Marchand, I.M. - **AUTOMATA 2023**